#### Name:



4.

Introduction:

# PhET 2D Motion and Vectors Simulations Lab rvsd 8/2010

A vector quantity is one that has both a magnitude and a direction. For instance, your car's velocity vector will have a magnitude (24 m/s) and a direction (northeast or 45 degrees). These simulations will illustrate how vectors are made of X and Y components, how two vectors can be added to produce a resulting vector, and how the acceleration vector affects the velocity vector in two-dimensional motion.



Trace

C Line Dots

Off

### **Part I: Vector Simulation:** Play With Sims $\rightarrow$ Physics $\rightarrow$ Motion $\rightarrow$ LadyBug 2D Motion Run Now!

Click Manual. Drag the bug around with your mouse and notice the actions of the two vectors. Spend some time investigating the vectors. Which vector is velocity?\_\_\_ \_\_\_\_\_ and which is acceleration?

#### 2. Be sure everyone in the lab group does ALL these exercises.

- 3. Describe the direction of the red vector (in relation to the green vector) when the bug sped up.
- What about the red vector when the bug *slowed down*?
- Click Circular. Observe the bug's motion. Where must the acceleration vector be (in relation to the velocity 5. vector) to turn the bug?
- Click *Ellipse*. Observe the bug moving like a car on a racetrack (in an oval). What must a car/runner do in order to turn? 6.
- 7. Now...use the **Remote Control** area to manually move the bug by controlling its position, velocity, and acceleration. Try to make the letter "C" three times using **position**, then **velocity**, then **acceleration**.
- Try to trace other letters, such as "O", "D", "S", "J", "P". Challenge your labmates! What can you trace using acceleration? 8.

### **<u>Part II: Vector Addition Simulation:</u>** Play With Sims $\rightarrow$ Math $\rightarrow$ Vector Addition **Run Now!**

in the work area. Change their direction and magnitude be dragging the heads of the arrows representing Place two vectors each vector. Click to view the resultant (sum) of the two vectors. You may click the *Styles* to show the X and Y components. Click on one vector and fill in the boxes: θ R Click on another vector and fill in the boxes: Vector Addition Click the **resultant** vector and fill in: \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_ \_  $|\mathbf{R}| =$ Magnitude of the vector (M)  $\theta =$  angle of the vector  $R_x = X$  component  $R_y = Y$  component Repeat with two different vectors: Vectors 1 and 2 The Resultant Vector Rx θ IR. θ IR  $\mathbf{R}_{\mathbf{v}}$  $|\mathbf{R}|$ θ R, R.

## Part III: Calculating Resultant Vectors: \*\*\*GRADED\*\*\*

Find the mathematical sum of each set of vectors below (with a calculator).

After you have calculated, recreate (as closely as possible) the vectors in the simulation to **check your work**.

#### Vector Components and Vector Addition Review:

- To add vectors, break each vector into its X an Y components by calculating  $M \cos \theta = X$  and  $M \sin \theta = Y$ . The components CAN BE NEGATIVE (-x, -y)
- The resultant vector's X and Y components are the sum of the X and Y components of each vector:  $X_r = X_1 + X_2$
- The resultant vector's *magnitude* M or  $|\mathbf{R}|$  is found using the Pythagorean theorem using  $X_r$  and  $Y_r$  as the legs of a right triangle, where the hypotenuse is the magnitude.
- The angle  $\theta$  of the resultant vector is found with the inverse tangent (tan<sup>-1</sup>) of the X<sub>r</sub> and Y<sub>r</sub> components.

Fill in all available boxes - exact, graded answers will come from calculations, use the sim to check your work

#1					#3	
Vector 1		-		-	Vector 1	
М	angle, θ	X <sub>1</sub>	Y <sub>1</sub>	-	М	angle
6.0	35					
Vector 2				-	Vector 2	
М	angle, θ	X2	Y <sub>2</sub>	-	М	angle
2.5	20.					
Resultant o	f adding vect	or 1 and vect	tor 2 compon	ents	Resultant	
Mr	θr	Xr	Yr		Mr	θr
#2				-	#4	
Vector 1	negativ	e angles - be	e careful	7	Vector 1	1
M	angle, θ	X1	Y1	-	М	angle
1.8	15.					70
Vector 2				-	Vector 2	
М	angle, θ	X2	Y <sub>2</sub>	-	М	angle
7.0	-25					-15
Resultant	•		•	-	Resultant	
Mr	θr	Xr	Yr		Mr	θr
					1	1

## 2D Motion Conclusion Questions:

1. The red vector represented \_\_\_\_\_

\_\_\_\_\_ and the green represented \_\_\_\_\_

- 2. When the acceleration vector was in the same direction as the velocity vector, the object slowed down / sped up.
- 3. When the acceleration vector was in the <u>opposite</u> direction as the velocity vector, the object *slowed down / sped up*.
- 4. Turning requires the acceleration vector to be directed where? \_\_\_\_\_
- 5. Imagine tracing the letter "J". As the ladybug is travelling down, it must turn to make *the hook*. In what direction must the acceleration vector point to move the velocity vector (from down) and trace the hook? \_\_\_\_\_\_

Vector 1							
М	angle, θ	X <sub>1</sub>	Y <sub>1</sub>				
		3.5	2.5				
Vector 2							
М	angle, θ	X2	Y <sub>2</sub>				
		4.0	6.0				
Resultant							
Mr	θr	Xr	Yr				

θ

θ

 $X_1$ 

4.7

X2

Xr

12.1

Y<sub>1</sub>

Y<sub>2</sub>

-2.0

Yr

10.8